## YS56-482100-220 Brushless DC Motor Product Datasheet

## YS56-482100-220 BLDC Overview

- Three Phase, Six Step, Full Wave, Y-Circuit
- Sintered Nd-Fe-B Permanent Magnet Rotor
- Hall Sensor / Sensorless
- Step (Cogging)
- Slot



Parameters	YS56-482100-220 BLDC Absolute Maximum Ratings	Unit
Peak Current	4.6	A
Speed	3000	rpm
Winding and Rotor Temperature	-20 to +130	$^{\circ}$
Ambient Temperature	-20 to +85	$^{\circ}$

Notice: The Absolute Maximum Ratings are those values beyond which the safety of the device cannot be guaranteed

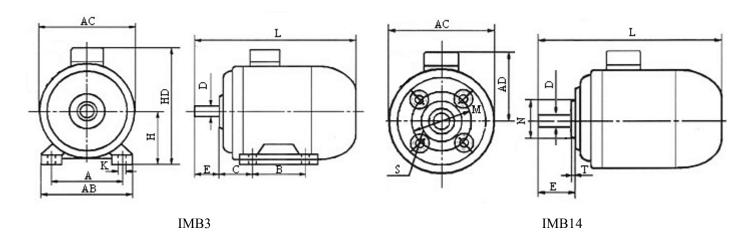
Parameters	YS56-482100-220 B	LDC Intrinsic Characteristics (20℃)	Unit
Resistance (Including 0.5m Line)		24	Ohm
Inductance (Including 0.5m Line)		43	mН
Speed-Torque Gradient		210	rpm/Nm
Torque Constant		1.10	Nm/A
Speed Constant		rpm/V	
Back-EMF Constant		mV/rpm	
Rotor Magnetic Poles		4	Poles
Ball Bearing No Load Continuous Life (At Nominal Voltage)	30000	(Please order if have special requirement)	Hours
Weight (Including 0.5m Line)	Approximate	3500	g

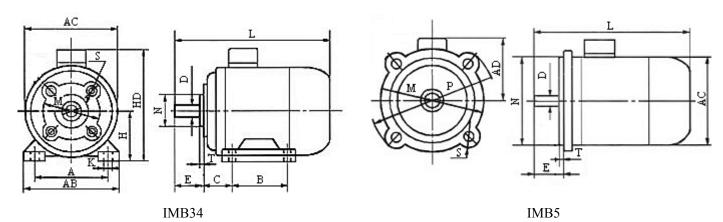


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## YS56-482100-220 BLDC Physical Size (Unit: mm)





IMB3	A	В	С	D	Е	Н	K	L	AB	AC	HD
IIVID3	90	71	36	9	20	56	7	190	115	110	140

IMB14	D	Е	L	M	N	S	T	AC	AD
IMD14	9	20	190	65	50	M5	2.5	110	80

IMB34	A	В	С	D	Е	Н	K	L	M	N	S	T	AB	AC	HD
IIVID34	90	71	36	9	20	56	7	190	65	50	M5	2.5	115	110	140

IMB5	D	Е	L	M	N	P	S	T	AC	AD
INIDS	9	20	190	100	80	120	9	2.5	110	80

• Feet: Removable

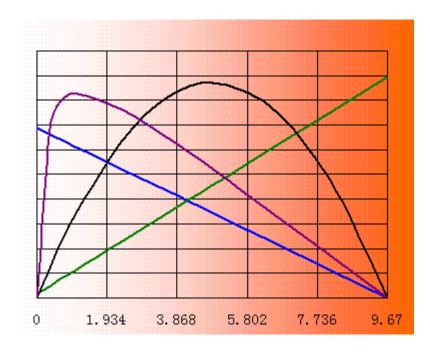
• Outer Shaft: Standard Dia 9, Max Dia 12



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Parameters	Parameters YS56-482100-220 BLDC Performance Characteristics (20℃)					Unit
Nominal Voltage	Nominal Voltage 220					V
Maximum Output Power (P2)		;	522			W
(See Curves Below)	No Load Point	Point Some Loaded Points Performance				
Output Torque (T)	0	1	1.3	1.7	2	Nm
Output Speed (N)	2060	1850	1790	1700	1640	rpm
Input Current (I)	0.16	1.07	1.34	1.70	1.98	A
Output Power (P2)	0	194	244	303	343	W
Efficiency (η)	0	83	83	81	79	%
Internal Fan	If the shell tempera	ature of the mo	otor is highe	r than 85℃,	more effect	ive cooling
Air Blast Cooling	equipments must be installed. Otherwise the motor may be damaged by hot					by hotness.



η(%)	<b>P2(W)</b>	I(A)	N(rpm)
100	600	10	3000
	E 001 1	700	

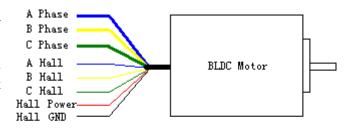
Efficiency vs. Torque:  $\eta$  -----Output Power vs. Torque: P2 -----Current vs. Torque: I -----Speed vs. Torque: N ------

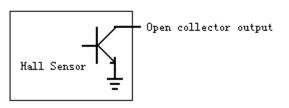


Torque (Nm)

### YS56-482100-220 BLDC Connection Diagram and Hall Output Waveforms

- Three Phases: AWG18, Blue thick--A phase, Yellow thick--B phase, Green thick--C phase
- Halls: AWG24, Blue thin--A hall, Yellow thin--B hall, Green thin--C hall, Red thin--Hall power supply, Black thin--Hall GND
- Hall Supply Voltage: 4.5 to 16VDC Regulated Supply
- Hall Power Supply Current: Less than 20mA
- Hall Output: Open collector. Require external pull-up resistors. Maximum output voltage is 16V
- Electrical Hall Sensor Phasing: 120°
- Line Length: 0.5m, (Please order if have special requirement)

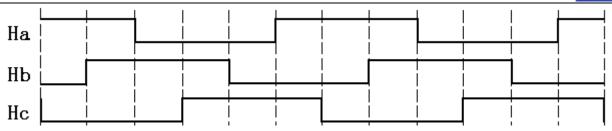






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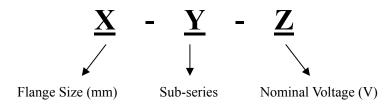
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Hall Sensor Output Commutation Waveforms

Notice: The A, B, C three windings and Ha, Hb, Hc three hall sensors must be connected correctly, otherwise the controller and motor may be damaged.

### **Eletechnic BLDC Motor Product Code Regulation**



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